

Ch 6: Many Particle Systems

Ex. 1:

Consider

$$r_1 = (1, 1, 1)$$

$$r_2 = (1, 0, 1)$$

$$r_3 = (0, 0, 1)$$

$$v_1 = (-1, 0, 0)$$

$$v_2 = (0, 2, 0)$$

$$v_3 = (1, 1, 1)$$

@ m

@ m

@ m

3 particles
positions & speeds

a. $\vec{r}_{cm} = \frac{m\vec{r}_1 + m\vec{r}_2 + m\vec{r}_3}{m+m+m} = \frac{1}{3}(\vec{r}_1 + \vec{r}_2 + \vec{r}_3)$

• $\vec{r}$ of CM: $= \frac{1}{3}((1, 1, 1) + (1, 0, 1) + (0, 0, 1))$

$\therefore \vec{r}_{cm} = \frac{1}{3}(2, 1, 3)$ ✓

b. $\vec{v}_{cm} = \frac{1}{m_T} \sum m_i \vec{v}_i = \frac{m}{3m}((-1, 0, 0) + (0, 2, 0) + (1, 1, 1))$

• $\vec{v}$ of CM: $\vec{v}_{cm} = \frac{1}{3}(0, 3, 1)$ ✓

c. the linear momentum of the system

• $\vec{p}$ of CM: $\vec{p} = m_T \vec{v}_{cm} = 3m \left(\frac{1}{3}(0, 3, 1) \right) = \underline{\underline{m(0, 3, 1)}}$ ✓

d. angular mom. about origin,

• $\vec{L}$ of system: $\vec{L} = \sum \vec{r}_i \times m_i \vec{v}_i = m \left[\begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 1 & 1 & 1 \\ -1 & 0 & 0 \end{vmatrix} + \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 1 & 0 & 1 \\ 0 & 2 & 0 \end{vmatrix} + \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 0 & 0 & 1 \\ 1 & 1 & 1 \end{vmatrix} \right]$
 $m[(0, -1, 1) + (-2, 0, 2) + (-1, 1, 0)] = \underline{\underline{m(-3, 0, 3)}}$ ✓

e. the kinetic energy

KE: $T = \frac{1}{2} \sum m_i (\vec{v}_i \cdot \vec{v}_i) = \frac{m}{2} \sum (v_{i1}^2 + v_{i2}^2 + v_{i3}^2) = \frac{m}{2}((1) + (4) + (3)) = \underline{\underline{4m}}$

6.2

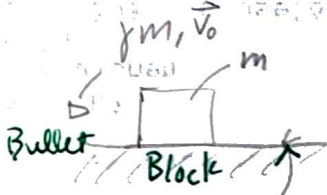


6/5 what is the recoil speed of the gun.

$$M v_0 = m v_g$$

$$v_g = \frac{m}{M} v_0$$

6.3



Q. What fraction of original KE is lost as heat, upon impact?

Q. how far will it slide before coming to rest?

$$T : \frac{1}{2} (m) v_0^2 + 0 = \frac{1}{2} m v_f^2 + \frac{1}{2} M v_f^2 \Rightarrow \frac{m}{2} v_0^2 = v_f^2 \frac{m}{2} (1 + \frac{M}{m})$$

$$v_f^2 = v_0^2 \frac{m}{1 + m}$$

$$\eta = 1 - \frac{v_f^2}{v_0^2} = 1 - \frac{m}{1 + m} = \frac{1}{1 + m}$$

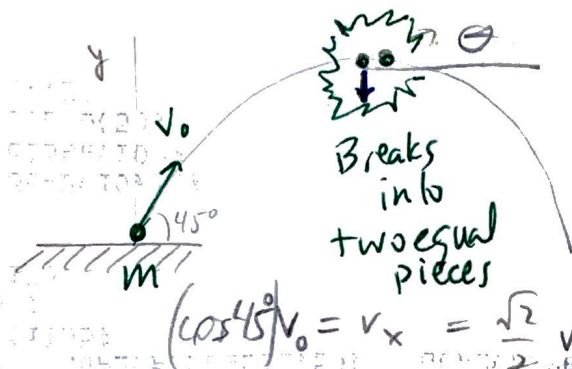
$$\eta = \frac{1}{1 + m}$$

$$\text{work do slide} = F_f \cdot d = \mu (m + M) g d$$

$$\text{work available KE} (1 - \eta) = \frac{m v_0^2}{2} (1 - \eta) = \mu (1 + m) g d$$

$$d = \frac{m v_0^2}{2 \mu (1 + m) g}$$

6.4



• 1st piece straight down @ $\sqrt{2} v_0$

Q: What is the direction and speed of the second particle?

At blast

$$\vec{p}_i = m v_x \hat{i}$$

what we want to find.

$$\vec{p}_f = \frac{m}{2} (\sqrt{2} v_0 \hat{j} + 0 \hat{i}) + \frac{m}{2} (v_x' \hat{i} + v_y' \hat{j})$$

$$\vec{p}_i = \vec{p}_f = \frac{m}{2} ((\sqrt{2} v_0 + v_y') \hat{j} + (0 + v_x') \hat{i}) \equiv m (v_x' \hat{i} + 0 \hat{j})$$

break into components:

$$\hat{j}: \frac{v_0 \sqrt{2} + v_y'}{2} = 0$$

$$v_y' = +v_0 \frac{\sqrt{2}}{2}$$

$$\hat{i}: \frac{v_x'}{2} = v_x$$

$$v_x' = 2v_x = \frac{\sqrt{2}}{2} v_0$$

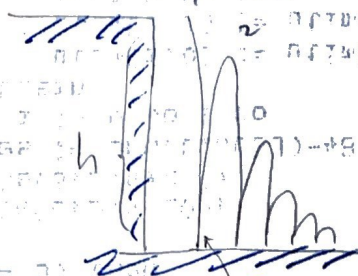
$$v' = v_0 \sqrt{(\frac{\sqrt{2}}{2})^2 + (\frac{\sqrt{2}}{2})^2} = \underline{\underline{2v_0}}$$

$$\text{direction } \tan \theta = \frac{v_y}{v_x} = 1$$

$$= \boxed{\theta = 45^\circ}$$

C.G

9



e , coefficient of restitution

Show total vertical distance before rebounds cease is

$$h \left(\frac{1+e^2}{1-e^2} \right)$$

(a) total vertical dist.

$$e = \frac{v_2}{v_1} = \frac{v_1}{v_2}$$

$$v_1 e = v_2$$

$$PE = KE$$

$$mgh_1 = \frac{1}{2} m v_1^2$$

$$v_1^2 = 2gh$$

$$h_1 = \frac{v_1^2}{2g}$$

$$\frac{1}{2} m v_{g1}^2 = mgh_2$$

$$h_2 = \frac{v_2^2}{2g} = \frac{v_1^2 e^2}{2g}$$

$$\frac{1}{2} m v_3^2 = mgh_3$$

$$h_3 = \frac{v_3^2}{2g} = \left(\frac{v_1 e^2}{v_1} \right)^2 \frac{1}{2g} = \frac{v_1^2 e^4}{2g}$$

$$h_T = \frac{v_1^2}{2g} + \frac{e^2}{e} \frac{v_1^2}{2g} + \frac{e^4}{e^2} \frac{v_1^2}{2g} + \dots$$

$$h_T = \frac{v_1^2}{2g} \sum_{n=0}^{\infty} e^{2n} = \frac{v_1^2}{2g} \cdot \frac{1}{1-e^2}$$

$$\frac{h_0}{1-e^2}$$

$$h = h_0 \left(\frac{2}{1-e^2} - 1 \right) = h_0 \left(\frac{2-1+e^2}{1-e^2} \right) = h_0 \left(\frac{1+e^2}{1-e^2} \right)$$

$$h \left(\frac{1+e^2}{1-e^2} \right) = h_T$$

finally

$$\sum_{n=0}^{\infty} x^n = \frac{1}{1-x} \quad \text{let } x = e^2$$

$$\sum_{n=1}^{\infty} e^{+2n} = \frac{1}{1 - \frac{1}{e^2}}$$

6:6 cont. (b) Total time elapsed

$$h_0 = \frac{1}{2} g t_1^2 \quad ; \quad \left(\frac{2 h_0}{g} \right)^{\frac{1}{2}} = t_1$$

$$v_1 h = \frac{1}{2} v^2$$

$$h = \frac{v^2}{g}$$

$$v_2 = \epsilon v_1$$

$$h_1 = \frac{v_2^2}{g} = \frac{1}{2} g t_2^2 \quad ; \quad 2 \left(\frac{2 v_2^2}{g^2} \right)^{\frac{1}{2}} = t_2 = 2 \left(\frac{2 \epsilon^2 v_1^2}{g^2} \right)^{\frac{1}{2}}$$

$$h_2 = \frac{v_3^2}{g} = \frac{1}{2} g t_3^2 \quad ; \quad 2 \left(\frac{2 v_3^2}{g^2} \right)^{\frac{1}{2}} = t_3 = 2 \left(\frac{2 \epsilon^4 v_1^2}{g^2} \right)^{\frac{1}{2}}$$

$$t_T = t_1 + t_2 + t_3 + \dots$$

$$= \left(\frac{2 h_0}{g} \right)^{\frac{1}{2}} + 2 \left(\frac{2 \epsilon^2 h_0}{g} \right)^{\frac{1}{2}} + 2 \left(\frac{2 \epsilon^4 h_0}{g} \right)^{\frac{1}{2}} + \dots$$

$$t_T = \left(\frac{2 h_0}{g} \right)^{\frac{1}{2}} + 2 \sum_{n=1}^{\infty} \left(\frac{2 h_0}{g} \epsilon^{2n} \right)^{\frac{1}{2}}$$

$$\text{let } \left(\frac{2 h_0}{g} \right)^{\frac{1}{2}} = L$$

$$t_T = L + 2 \sum_{n=1}^{\infty} L \epsilon^n = L (1 + 2 \sum_{n=1}^{\infty} \epsilon^n) = L \left(1 + \frac{2}{1 - \epsilon^2} \right)$$

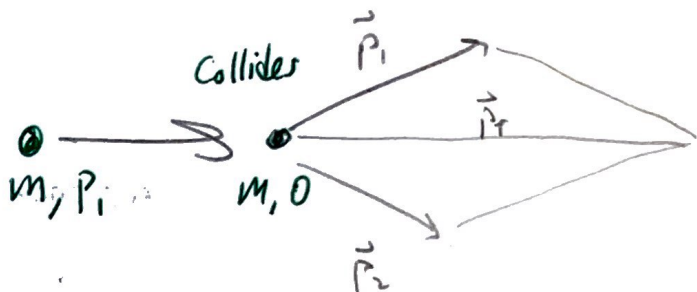
$$t_T = \sqrt{\frac{2 h_0}{g}} \left(\frac{3 - \epsilon^2}{1 - \epsilon^2} \right)$$

$$\sqrt{\frac{2 h}{g}} \quad \frac{1 + \epsilon}{1 - \epsilon}$$

please
see the key

G.17

$$\frac{(\vec{P}_i)^2}{2m} = \frac{(\vec{P}_1')^2}{2m} + \frac{(\vec{P}_2')^2}{2m}$$



Find Total energy loss, Q

$$\vec{P} \Rightarrow \vec{P}_i = \vec{P}_1' + \vec{P}_2'$$

$$E \Rightarrow \frac{P_i^2}{2m} = \frac{P_1'^2}{2m} + \frac{P_2'^2}{2m} + Q$$

$$P_i^2 = P_1'^2 + P_2'^2 + 2mQ$$

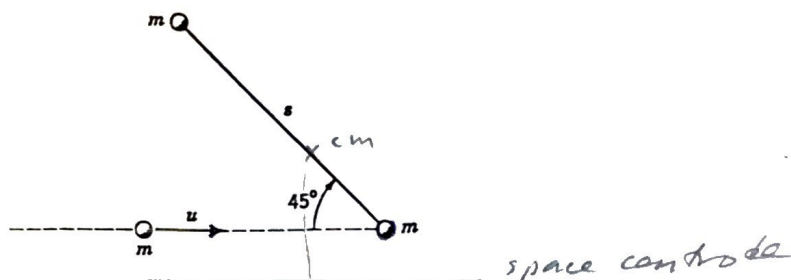
$$\text{law of cosines} \Rightarrow -2P_1'P_2'\cos\psi$$

$$Q = \frac{P_1'P_2'\cos\psi}{m}$$



Problem from Bradbury:

8.14.34 Two particles of mass m are at rest and connected by a rigid massless rod of length s . A third particle also of mass m , and moving with a velocity u



at an angle of 45° with the rigid rod, strikes one of the particles and sticks to it as in the figure. Find the linear velocity of the center of mass and the angular velocity of rotation of the system after the collision. Locate the space centre.

Conservation of linear momentum:

$$mu = 3m v_c \Rightarrow \underline{v_c = \frac{1}{3} u}$$

CM is $\frac{1}{3}s$ up from lower mass after third particle sticks to rigid body.

Conservation of angular momentum about this point (which is CM right after collision):

$$mu \underbrace{\frac{s}{2\sqrt{2}}}_{\text{vertical distance from line of } u \text{ to CM}} = I_c \omega = m \left[2 \left(\frac{s}{3} \right)^2 + \left(\frac{2s}{3} \right)^2 \right] \omega = \frac{2}{3} m s^2 \omega$$

$$\Rightarrow \underline{\omega = \frac{u}{2\sqrt{2} s}}$$

space centre: $b\omega = v_c$

$$\Rightarrow \underline{b = \frac{2\sqrt{2}}{3} s}$$

Roy W. Erickson

PHYSICS 321

TAKE-HOME QUIZ

NOV. 13, 1981

Due: 1:10 p.m., Nov. 16

Open Book - you may use your text, notes, and problem solutions.
You may also use math tables. You may not use any
other books or consult with anyone except Dr. Evenson.

1. A proton of mass m_p with initial velocity v_0 collides with a helium atom, mass $4m_p$, that is initially at rest. If the proton leaves the point of impact at an angle of 45° with its original line of motion, find the final velocities of each particle.

Assume that the collision is inelastic and that Q is equal to $1/4$ of the initial energy of the proton.

Solve the problem in the lab frame. Start from first principles.

see attached 1st, then back

In c.m. frame

$$\underline{\underline{\bar{V}_1}} = \frac{m_2 \vec{V}_1}{m_1 + m_2} \Rightarrow \frac{4m_p V_0}{m_p + 4m_p} = \underline{\underline{\frac{4}{5} V_0}}$$

From text p179 eq 6.47

$$V_1' \frac{\sin \varphi_1}{\sin \theta} = \bar{V}_1'$$

$$V_1' \left(\frac{\sin 45^\circ}{\sin 32.690^\circ} \right) = \bar{V}_1'$$

$$V_1' (.5401) = \bar{V}_1' \quad (4)$$

From text p179 eq. 6.42

$$\frac{\bar{P}_1^2}{2m} = \frac{\bar{P}_1'^2}{2m} + Q$$

$$M = \frac{m_1 m_2}{m_1 + m_2} = \frac{4}{5} m_p$$

$$\rightarrow \frac{m_p^2 \left(\frac{4}{5} V_0 \right)^2}{2 \cdot \frac{4}{5} m_p} = \frac{m_p^2 \bar{V}_1'^2}{2 \cdot \frac{4}{5} m_p} + \left\{ Q = \frac{1}{4} \left(\frac{1}{2} m_p V_0^2 \right) \right\}$$

$$\frac{\frac{2 \cdot 16}{5} \frac{V_0^2}{5}}{\frac{8}{5}} = \frac{5}{8} \bar{V}_1'^2 + \frac{1}{8} V_0^2$$

$$\rightarrow \frac{6}{5} V_0^2 - \frac{5}{8} \bar{V}_1'^2 = ? \quad \text{use (4)}$$

Test
This
eq for

Both $V_1' \rightarrow + \Rightarrow V_1' \rightarrow c = .42$
 $V_1' \rightarrow - \Rightarrow V_1' \rightarrow c = .84$

$$+ \left] \frac{2}{5} - \frac{5}{8} (.42)^2 (.5401)^2 = .37 \right.$$

$$- \left] \frac{2}{5} - \frac{5}{8} (.8405)^2 (.5401)^2 = .27 \leftarrow \text{close} \right.$$

well I guess the "-" case.

$V_1 = .84 V_0$ $V_2 = .104 V_0$

$$\underline{\underline{\gamma}} = \frac{m_p}{4m_p} \left[1 - \frac{1}{4} \left(1 + \frac{m_p}{4m_p} \right) \right]^{-\frac{1}{2}} = \frac{1}{4} \left[1 - \frac{1}{4} \left(\frac{5}{4} \right) \right]^{-\frac{1}{2}} = \frac{\sqrt{16}}{4\sqrt{11}} \rightarrow \underline{\underline{1}}$$

$$\tan \varphi_1 = \frac{\sin \theta}{\gamma + \cos \theta} = \tan 45^\circ = 1$$

-or-

$$\sin \theta = \gamma + \cos \theta$$

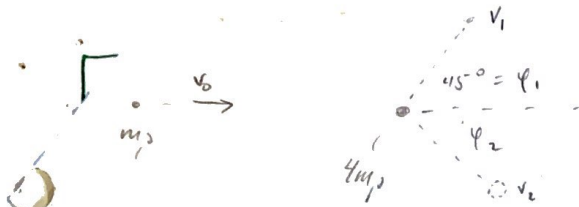
$$\left[\sin \theta - \cos \theta = \gamma \right]^2$$

$$\sin^2 \theta - 2 \sin \theta \cos \theta + \cos^2 \theta = \gamma^2$$

$$1 - \sin 2\theta = \gamma^2$$

$$\frac{\sin^{-1}(1 - \gamma^2)}{2} = \theta$$

$$\underline{\underline{\theta}} = \frac{\sin^{-1}(1 - \frac{1}{11})}{2} = \underline{\underline{32.690}}$$



What are the final velocities of each particle

Two equations: $KE_i = KE_f + Q$

$$\frac{1}{2} m_1 v_0^2 = \frac{1}{2} m_1 v_1^2 + \frac{1}{2} 4m_1 v_2^2 + \frac{1}{4} \left(\frac{1}{2} m_1 v_0^2 \right) \checkmark$$

or

$$\boxed{\frac{3v_0^2}{4} = v_1^2 + 4v_2^2} \quad (1)$$

$$\vec{P}_i = \vec{P}_f$$

$$m_1 \vec{v}_0 = m_1 \vec{v}_1 + 4m_1 \vec{v}_2$$

or

$$v_0 \begin{pmatrix} 1 \\ 0 \end{pmatrix} = v_1 \begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix} + 4v_2 \begin{pmatrix} \cos \phi_2 \\ -\sin \phi_2 \end{pmatrix}$$

separates to

$$\boxed{v_0 = \frac{v_1}{\sqrt{2}} + 4v_2 \cos \phi_2} \quad (2)$$

$$\boxed{0 = \frac{v_1}{\sqrt{2}} - 4v_2 \sin \phi_2} \quad (3)$$

three equations, three unknowns:

$$\text{eq. 3} \Rightarrow \underline{\underline{\sin \phi_2 = \frac{v_1}{4\sqrt{2} v_2}}}$$

$$\text{eq 2} + (-\text{eq 3}) \Rightarrow v_0 = 4v_2 (\cos \phi_2 + \sin \phi_2)$$

$$v_0^2 = 16v_2^2 (1 + 2\cos \phi_2 \sin \phi_2)$$

$$= 16v_2^2 \left(1 + 2\sqrt{1 - \left(\frac{v_1}{4\sqrt{2} v_2} \right)^2} \left(\frac{v_1}{4\sqrt{2} v_2} \right) \right)$$

$$= 16v_2^2 + \left(\frac{16^2 v_2^2 \cdot 4 \cdot v_1^2}{16 \cdot 2 v_2^2} - \frac{2 \cdot 2 v_1^2 \cdot 16^2 v_2^4 v_1^2}{16 \cdot 2 v_2^2 \cdot 16 \cdot (2 v_2^2)} \right)^{1/2}$$

$$(v_0^2 - 16v_2^2)^2 = [32v_2^2 v_1^2 - v_1^4]$$

$$v_0^4 - 2 \cdot 16v_2^2 v_0^2 + 16^2 v_2^4 - 32v_2^2 v_1^2 + v_1^4 = 0$$

$$\text{eq 1} \Rightarrow v_1^2 = \frac{3}{4} v_0^2 - 4v_2^2$$

In

$$v_0^4 - 32v_2^2 v_0^2 + 16^2 v_2^4 - 32v_2^2 \left[\frac{3}{4} v_0^2 - 4v_2^2 \right] + \left[\frac{3}{4} v_0^2 - 4v_2^2 \right]^2 = 0$$

$$v_0^4 - 32v_2^2 v_0^2 + 16^2 v_2^4 - \frac{32 \cdot 3 v_2^2 v_0^2}{4} + \frac{4 \cdot 32 v_2^4}{4} + \left[\frac{9}{16} v_0^4 - \frac{2 \cdot 3 \cdot 4}{4} v_0^2 v_2^2 + 16 v_2^4 \right] = 0$$

From text

$$v_1' \sin \varphi$$

$$\sin \theta$$

$$v_1' \left(\frac{\sin 45}{\sin 32} \right)$$

$$v_1' (.540)$$

$$v_0^4 \left[1 + \frac{9}{16} \right] + v_0^2 v_2^2 \left[-32 - 24 - 6 \right] + v_2^4 \left[16^2 + 128 + 16 \right] = 0$$

$$v_0^4 [16 + 9] + v_0^2 v_2^2 [-62] + v_2^4 [400] = 0$$

$$v_0^4 10 - v_0^2 v_2^2 99.2 + v_2^4 640 = 0$$

$$v_0^4 - v_0^2 v_2^2 99.2 + v_2^4 640 = 0$$

$$a = 640$$

$$b = -99.2$$

$$c = 1$$

From text

$$\bar{P}_1^2$$

$$2m$$

$$M =$$

$$v_2^2 = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

$$v_2^2 = \frac{99.2 \pm \sqrt{(99.2)^2 - 4(640)(1)}}{2(640)} v_0^2$$

$$v_2^2 = \frac{99.2}{1280} v_0^2 \pm \frac{85.33}{1280} v_0^2$$

$$v_2^2 = (0.775 \pm 0.06661) v_0^2$$

$$+ : v_2 = 0.379 v_0$$

$$- : v_2 = 0.1044 v_0$$

from eq(1):

$$v_1 = \sqrt{\frac{3}{4} v_0^2 - 4v_2^2}$$

$$+] v_1 = \sqrt{\frac{3}{4} - 4(0.379)^2} v_0 = 0.42 v_0$$

$$-] v_1 = \left(\frac{3}{4} - 4(0.1044)^2 \right)^{1/2} v_0 = 0.84 v_0$$

Total KE

$$.41885$$

Test
This
eq for

Both v_1'

SEE BACK OF PROBLEM
SHEET.

6.18

Rocket fired upward

a) Find eq. of motion -

b) Find ratio $\left(\frac{m_{fuel}}{m_{payload}}\right)$ if $v_f = v_e$; $V = kv_e$, $\dot{m} = \dot{m}_i$

c) Find numerical ratio if $k = \frac{1}{4}$; $\frac{m_{f_0}}{\dot{m}_i} = 100$

a) For variable mass

$$\vec{F} = m\vec{\ddot{z}} + \vec{V}\dot{m} \Rightarrow -mg = m\ddot{z} + V\dot{m}$$

$$\ddot{z} = -g - \frac{V\dot{m}}{m(t)}$$

$$\begin{aligned} dz &= (-g - V\frac{\dot{m}}{m})dt \\ &= -gdt - V\frac{dm}{m} \end{aligned}$$

$$\text{or } \int_0^V dv = -gt - V \ln m \Big|_{m_0}^m = -gt - V \frac{m(t)}{m_0}$$

so
$$v(t) = -gt - kv_e \ln \frac{m_{mf}(t)}{m_{mf}(0)}$$

$m(t) = m_0 + \dot{m}t$ when all fuel is gone $m(t_f) = m_{payload}$

$$m_p = m_0 + \dot{m}t_f \rightarrow t_f = \frac{m_p - m_0}{\dot{m}}$$

$$V(t_f) \equiv v_e \text{ i.e. } v_e = -g \left(\frac{m_p - m_0}{\dot{m}} \right) - kv_e \ln \frac{m_p}{m_0}$$

which is written as
$$e^{\left[\frac{1}{k} + \frac{gm_f}{\dot{m}kv_e} \right]} = \frac{m_p + m_f}{m_p} = 1 + \frac{m_f}{m_p}$$

therefore

$$\frac{m_f}{m_p} = e^{\left(\frac{1}{k} + \frac{gm_f}{\dot{m}kv_e} \right)} - 1$$

$$\frac{m_f}{m_p} = e^{\left(4 + 40 \log_3 \left(\frac{9.8 \text{ m/s}^2}{1.1 \times 10^4 \text{ m/s}^2} \right) \right)} - 1 = \underline{\underline{53.8}} \quad ??$$